

### TIME SERIES ANALYSIS FOR ENERGY DATA

# M10 - State Space Models / Bayesian Framework

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# Learning Goals

- Discuss state space models in general
- Discuss Bayesian Framework
- Learn about local level, linear trend and basic structure models
- See how models we are familiar with fit under state space framework (linear regression, exponential smoothing)
- Implement state space model in R



# What's next?

Forecasts from ARIMA(1,0,0)(0,1,1)[12] with drift

- After you have done the simple model, you start thinking about ways to improve it
- Other forecasting techniques can help make the model more accurate
- Suppose the variable is highly dependent on other factors, such as weather, holidays, time of the day, etc. One could try fitting time series models that allow for inclusion of other predictors using methods such
  - ARMAX (still a linear regression but with exogenous predictors)

$$y_{t} = \beta_{1}x_{t} + \phi_{1}y_{t-1} + \dots + \phi_{p}y_{t-p} + a_{t} - \theta_{1}a_{t-1} - \dots - \theta_{q}a_{t-q}$$

### More general models

- State Space models
  - Model not only the variable but also the coefficients
  - Bayesian approach to state space models
    - Ex: Dynamic Linear Models



### State Space Models

- The State Space Model approach offers a very general and powerful framework to operate with time series data
- Models with time-varying parameters can be created

- Classical linear regression is embedded as special case
- ARIMA-model class is also a special case

### State Space Models (cont'd)

- State Space models allow decomposition of a time series into relevant components – trend, cycle, seasonal
- And analyze each in real-time (filter), to infer best historical estimates (smoothing), and to forecast all components as well as the original series

# State Space Models (cont'd)

Main estimation algorithm, Kalman Filter, is set-up as recursive form



Approach allows to include a priori knowledge through a suitable Bayesian formulation of the initial state vector

#### A little background: Bayesian Statistics

- Frequentist versus Bayesian statistic
- Different way of thinking
- Instead of asking: What is the likelihood of this data point given the model (frequentist), the Bayesian ask: What is the likelihood of the model given this data point?





#### Simple Example (Bayesian approach)

- Two frogs: Joe (P(feet) = 0.6) and Herman (P(feet) = 0.2)
- Pick one frog and "jump" it. It lands on its feet. What is the probability it is Joe?





#### Simple Example (Frequentist approach)

Find which distribution you could use to model the problem



#### **Bayesian Framework**



# Back to State Space Models

#### **Time Series Decomposition**

Classical decomposition of a time series

$$y_t = \mu_t + \gamma_t + \varepsilon_t$$
,  $t = 1, ..., n$ 

where

 $y_t$ : observation

 $\mu_t$ : slowly changing (trend) component

- $\gamma_t$ : seasonal component
- $\varepsilon_t$ : error term (random)

Component can be determinist (ARIMA) or functions of time (stochastic)

### Local Level (LL) Model

#### Deterministic Example

 $y_t = \mu + \varepsilon_t$  where  $\varepsilon_t$  are *i.i.d* and  $\varepsilon_t \sim N(0, \sigma_{\varepsilon}^2)$  or  $\varepsilon_t \sim \mathcal{NJD}(0, \sigma_{\varepsilon}^2)$ 

Stochastic Example

 $y_t = \mu_t + \varepsilon_t \qquad \varepsilon_t \sim \mathcal{NID}(0, \sigma_{\varepsilon}^2)$ 

If  $\mu_t$  is a function of time, we also need a model for  $\mu_t$ 

 $\mu_{t+1} = \mu_t + \eta_t \qquad \eta_t \sim \mathcal{NID}(0, \sigma_\eta^2)$ 

What do we need to specify?

Parameters:  $\mu_1 \sim N(a, P)$  and  $\sigma_{\varepsilon}^2$ ,  $\sigma_{\eta}^2$ 

# Local Linear Trend (LLT) Model

#### Stochastic Example

 $y_t = \mu_t + \varepsilon_t$  $\mu_{t+1} = \beta_t + \mu_t + \eta_t$  $\beta_{t+1} = \beta_t + \xi_t$ 

$$\begin{split} & \varepsilon_t \sim \mathcal{NJD}(0, \sigma_{\varepsilon}^2) \\ & \eta_t \sim \mathcal{NJD}(0, \sigma_{\eta}^2) \\ & \xi_t \sim \mathcal{NJD}(0, \sigma_{\xi}^2) \end{split}$$

What do we need to specify?

Parameters: prior distributions  $\mu_1$ ,  $\beta_1$  and  $\sigma_{\varepsilon}^2$ ,  $\sigma_{\eta}^2$ ,  $\sigma_{\xi}^2$ 

- Special cases:
  - If  $\sigma_{\eta}^2 = \sigma_{\xi}^2 = 0$ , the trend is a straight line with slope  $\beta_1$  and intercept  $\mu_1$

• If  $\sigma_{\eta}^2 = 0$  and  $\sigma_{\xi}^2 > 0$ , the trend is a smooth curve

# Local Trend with Seasonality Model

Also known as Basic Structural Model or BSM

 $y_t = \mu_t + \gamma_t + \varepsilon_t$   $\mu_{t+1} = \beta_t + \mu_t + \eta_t$   $\beta_{t+1} = \beta_t + \xi_t$  $\gamma_{t+1} = -\sum_{j=1}^{s-1} \gamma_{t+1-j} + \omega_t$   $\begin{aligned} \varepsilon_t \sim \mathcal{NJD}(0, \sigma_{\varepsilon}^2) \\ \eta_t \sim \mathcal{NJD}(0, \sigma_{\eta}^2) \\ \xi_t \sim \mathcal{NJD}(0, \sigma_{\xi}^2) \\ \omega_t \sim \mathcal{NJD}(0, \sigma_{\omega}^2) \end{aligned}$ 

S denote number of seasons

#### □ What do we need to specify?

Parameters: prior distributions  $\mu_1, \beta_1, \gamma_1, \dots, \gamma_s$  and  $\sigma_{\varepsilon}^2, \sigma_{\eta}^2, \sigma_{\xi}^2, \sigma_{\omega}^2$ 

#### Special case

If  $\sigma_{\omega}^2 = 0$ , the seasonal component is determinist, i.e., dummy coefficient's do not change over time

### Exponential Smoothing under SS

#### Model equations will be

Observation equation  $y_t = l_t$ 

 $\varepsilon_t \sim \mathcal{NJD}(0, \sigma_{\varepsilon}^2)$ 

State equation

 $l_t = l_{t-1} + \alpha \varepsilon_t$ 

#### Linear Regression State Space Model

**Observation**  $Y_t = F_t' \theta_t + v_t$ equation  $v_t \sim \mathcal{NID}(0, \sigma_n^2)$ 

State equation  $\theta_{t+1} = G_{t+1}\theta_t + W_{t+1}$  $W_{t+1} \sim \mathcal{NID}(0, \sigma_w^2)$ 

- What do we need to specify?  $\{F_t, G_t, \sigma_v^2, \sigma_w^2\}$ 
  - **Common approach is to make**  $G_t$ constant and equal to identity matrix (random walk)

- What about priors?
  - Find initial parameters for  $\theta_0$  based on initial information

$$\theta_0/D_0 \sim N(m_0, C_0)$$

Ex. Use the initial observations and run linear regression to get prior for the mean and variance of coefficients

# State Space Forecasting in R

- Exponential Smoothing in State Space Model package "smooth"
- Similar to the function ses() but with time varying parameters

es(data, model = "ZZZ", persistence = NULL, phi = NULL, initial = c("optimal", "backcasting"), initialSeason = NULL, ic = c("AICc", "AIC", "BIC"), cfType = c("MSE", "MAE", "HAM", "MSEh", "TMSE", "GTMSE", "MSCE"), h = 10, holdout = FALSE, cumulative = FALSE, intervals = c("none", "parametric", "semiparametric", "nonparametric"), level = 0.95, intermittent = c("none", "auto", "fixed", "interval", "probability", "sba", "logistic"), imodel = "MNN", bounds = c("usual", "admissible", "none"), silent = c("all", "graph", "legend", "output", "none"), xreg = NULL, xregDo = c("use", "select"), initialX = NULL, updateX = FALSE, persistenceX = NULL, transitionX = NULL, ...)

- model three-character string
  - The first letter denotes the error type ("A", "M" or "Z");
  - the second letter denotes the trend type ("N","A","M" or "Z"); and
  - □ the third letter denotes the season type ("N","A","M" or "Z").

"N"=none, "A"=additive, "M"=multiplicative and "Z"=automatically selected

# State Space Forecasting in R

#### General class

package "stats"

StructTS(<mark>x, type = c("level", "trend", "BSM")</mark>, init = NULL, <mark>fixed = NULL</mark>, optim.control = NULL)

- Structural time series models are (linear Gaussian) state-space models for (univariate) time series based on a decomposition of the series into the components
  - □ type ="level" local level model
  - type ="trend" local linear trend model
  - type ="BSM" basic structural model, i.e., local trend with seasonal component

# StrucTS() explained

StrucTS( data, type="BSM", fixed=c(0.1,0.001,NA,NA) )

 $y_t = \mu_t + \gamma_t + \varepsilon_t$   $\mu_{t+1} = \beta_t + \mu_t + \eta_t$   $\beta_{t+1} = \beta_t + \xi_t$  $\gamma_{t+1} = -\sum_{j=1}^{s-1} \gamma_{t+1-j} + \omega_t$  
$$\begin{split} \varepsilon_t \sim \mathcal{NJD}(0, \sigma_{\varepsilon}^2) \\ \eta_t \sim \mathcal{NJD}(0, \sigma_{\eta}^2) \\ \xi_t \sim \mathcal{NJD}(0, \sigma_{\xi}^2) \\ \omega_t \sim \mathcal{NJD}(0, \sigma_{\omega}^2) \end{split}$$

□ Fixed argument refers to variances □ fixed=c( $\sigma_n^2$ ,  $\sigma_{\xi}^2$ ,  $\sigma_{\omega}^2$ ,  $\sigma_{\varepsilon}^2$ ,)



# THANK YOU !

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